# **SOLUTIONS IN MOTION®**





# Pro-face HMI with MotoEIP

### **GRAPHICAL HMI WITH DX100**

Pro-face with MotoEIP is a Human Machine Interface (HMI) option for DX100 robot controllers. This display is connected directly to the controller using MotoEIP. MotoEIP gives the DX100 robot controller the ability to communicate using EtherNet/IP (Industrial Protocol) without the need for additional hardware. A set of screens are provided as templates, and 5.7 inch or 10.4 inch displays are available. Pro-face HMI can be pedestal or fence mounted.

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ROBOT POSITION DATA



# **TOP 3 REASONS TO BUY!**

- Ideal for applications requiring an HMI and no PLC
- Cost-effective HMI solution for robotic systems
- Customizable for specific application requirements

#### **Display Features**

- 65,536 colors; TFT display
- 10 Base-T/100 Base-TX Ethernet, USB Serial (MPI) and CompactFlash® interfaces
- GP-Pro EX HMI development environment (not included)

#### 5.7" Display Features

- Graphical touch screen
- 320 x 240 resolution
- Ethernet/internet remote connectivity
- Multi-language support
- Dual simultaneous protocol support

#### 10.4" Display Features

- 640 x 480 and 800 x 600 resolution
- 64-bit RISC 266 Mhz CPU for ultra fast screen refresh and data sampling
- No-grid analog touch panel for improved visibility and precise touch placement

## HIGHLIGHTS

- Supports up to four protocol drivers simultaneously
- High-speed application transfer; 10 times faster than conventional operator interfaces
- Audio output, alarm, buzzer, remote reset interfaces
- Video camera support using optional GP2000-VM41 video mix module

#### **Communication Features**

- Class 3 explicit message server
- Class 1 I/O implicit messaging
- Fully compatible with ODVA standards
- Fully compatible with Pro-face HMI explicit messaging driver

#### DX100 object models include:

- DX100 B Variable Object
- DX100 | Variable Object
- DX100 D Variable Object
- DX100 R Variable Object
- DX100 M Register Object
- DX100 Position Variable Object

(Contact Motoman Robotics for complete listing)

Explicit messaging connection

robot controller on demand.

to query robot position, set

variable data, start/stop robot

produces an average explicit

message response time of

jobs and more. This high-speed

sends commands to the

Commands can be used

communication interface

12 milliseconds

...with Motoman Robotics'

graphical user interface for

Pro-face HMI to create a

your robotic application.

NOTE: Not compatible with

EtherNet/IP card

**ARM YOURSELF** 

- DX100 CIO Object
- DX100 Alarm Object
- DX100 System Status Object
- DX100 Job Control Object
- DX100 Robot Position Object

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